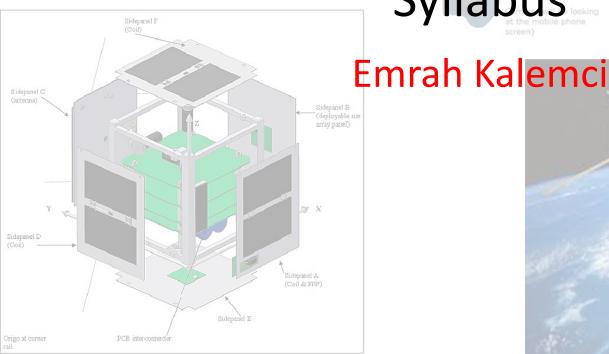
ENS 303 Introduction to Space Technology

Syllabus



ladir Sensor earth horizon

General Information

Lecture hours:

- Monday 13:40-15:30
- <u>https://sabanciuniv.zoom.us/j/91782329116?pwd=UE80</u>
 <u>RkNBU1FqYjdhUnl0T0dWbTUyUT09</u>
- Tuesday 8:40 09:30

https://sabanciuniv.zoom.us/j/94446242203?pwd=ZXM1b HZaNIRCaFdVVjFBRm5qS1owdz09

Cattern TOPHAT ID: 214678

Office hours: None. Just send me an e-mail if you want to talk to me, anytime. I will arrange an online meeting

Pulsed Plasma Thruster (PPT) Thruster Electrodes Grading

ladir Sensor earth horizon ensor) Pulsed Plasma Thruster (PPT) Power Module

> Pulsed Plasma Thruster (PPT) Thruster Electrodes

- Project : 60 pts
- Final : 30 pts
- Class + Tophat performance : 20 pts

idepanel A

Final includes simple problems from lectures, and short answer questions from the course material.

Class performance: I or a TA will monitor your activity in class, and based on your questions and Tophat participation you will get a bonus.

Project

Nadir Sensor (earth horizon Pulsed Plasma Thruster (PPT) Power Module

- You will decide on a CubeSat project, or work on a project I suggest.
- You will design the CubeSat as a team. I will be your systems engineer/manager/PI.
- After determining the mission objectives and functional requirements, you will create the first version of the functional block diagram.
- You will produce engineering tasks related to the functional block diagram, and then create a Gannt Chart. I determine the milestones for timely execution of the project. Your schedule must fit into the milestones.
- Each of you will lead a specific task in the schedule. The project will be managed by a software called **dotproject**. Every time you work on the project, you will enter a log. I expect at least one log every week, if not more.
- Your project grade will be based on these logs, and your adherence to milestones and deadlines set in the project.
 - Monday lectures (except the first 2) will be to discuss the progress in the project. I WILL TAKE ATTENDANCE. We will try to solve problems together and decide on trade-offs. If I feel that you have done enough on a task, I will stop it (as some tasks may require more experience and skills than you may have)
- The end-product should be a complete set of tasks that could in principle lead to an actual cubesat system, and a preliminary design review that discusses feasibility issues. While the aim is to understand how it is done, rather than actually doing it, some components you worked on may be part of the actual cubesat. IF THE PROJECT is GOOD ENOUGH, WE WILL AIM for MI CONTEST!

PCB inter

Sidepanel D (Coil) —

adir Sensor earth horizon Pulsed Plasma Thruster (PPT) Power Module

General Milestones

- March 14 Brainstorming on cubesat idea
- March 21 Cubesat idea finalized
- March 28 Teams established

ends.

April 11 – Functional Requirements

High performance computing board WiFi Tranceiver (will be communicati with mobile phone)

 April 18 – Functional block diagram and finalizing schedule and tasks.

June 6 – Preliminary Design Review – project

Resources

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- Lecture notes will be placed on SUCOURSE, lecture videos will be shared
- Books on reserve:
 - The Space Environment: Implications for Spacecraft Design Alan C. Tribble
 - Space Mission Analysis and Design, 3rd edition

Wiley J. Larson (Editor), James R. Wertz (Editor)

Spacecraft Systems Engineering

Peter Fortescue (Editor), Graham Swinerd (Editor), John Stark (Editor)

• In my room ?:

Space Vehicle Design

Michael D. Griffin, James R. French

- Introduction to Space Science
- Additional links, lecture notes and web resources will be placed on SUCOURSE
- hansolo.sabanciuniv.edu/dotproject will be the project managing web site once you decide on the mission. I will send you passwords.
- There is endless information on Cubesats on the internet.

WiFi Tranceiver (will be communicati with mobile phone)

Pulsed Plasma Thruster (PPT Thruster Electrodes

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Lecture subjects

- Introduction to space system design
- Orbits
- Space and spacecraft environment
- Power

Sidepanel D (Coil) - Camera (will be looking at the mobile phone screen) teaction wheel brushless DC motor vith spinning disc)

High performance computing board ViFi Tranceiver (will be communicati with mobile phone)

Attitude determination and control

Communications and telemetry

Launch vehicles and orbital dynamics

• Application examples

Pulsed Plasma Thruster (PPT) Power Module

TOPHAT and Class Participation

- Thruster (PPT) Thruster Electrodes
- Many of the lectures are already on record from 2020 spring. All lectures will be recorded.
 Some lectures will be "flipped" as you will first watch the lecture and answer Tophat

questions in class.

JOIN CODE: 214678

Camera (will be looking at the mobile phone screen) eaction wheel orushless DC motor ith spinning disc)

High performance computing board WiFi Tranceiver (will be communicatin with mobile phone)

Let's try a test question on Tophat...